

# Reinforcement Learning

## Chapter 7: Applications and Advancements in DRL

Ali Bereyhi

`ali.bereyhi@utoronto.ca`

Department of Electrical and Computer Engineering  
University of Toronto

Fall 2025

# Story of RL

1950s

Dynamic Programming  
Richard Bellman

1960s

Going Model-free  
Monte-Carlo Methods

1970s

Temporal Difference  
Richard Sutton

DQL

DeepMind played Atari games  
Performed better than human

New Era for Deep RL

OpenAI proposed TRPO and PPO  
OpenAI's Gym made implementation easy  
DeepMind proposed AlphaZero  
PyTorch and TensorFlow developed RL packages

2013

DQL

2015+

TRPO and PPO by OpenAI  
OpenAI Gym  
DeepMind's AlphaZero

Early Developments

Bellman Equations  
Understanding Model-based RL

First Model-free RL Approaches

Monte Carlo method  
No use of Bellman

Bootstrapping

Connecting DP to Monte-Carlo

# DeepMind: Inspiring RL Group

*DeepMind doubtlessly is a key actor in Deep RL*

- Founded in **September 2010**
- Used **DQL** to play Atari games in **2013**
  - ↳ A breakthrough in the area of RL: introducing deep RL
- Google buys DeepMind in **2015**
- Introducing AlphaGo in **2015**
  - ↳ Beats European master player
- Introducing AlphaGo Zero as an improved version of Alpha Go in **2017**
- Introducing AlphaZero as a general algorithm in **2017**
  - ↳ It can play superhuman level Go, Chess and Shogi after 24 hours of training

# DeepMind: Inspiring RL Group

## LETTER

doi:10.1038/nature14236

### Human-level control through deep reinforcement learning

#### Playing Atari with Deep Reinforcement Learning

Volodymyr Mnih<sup>1</sup>\* Koray Kavukcuoglu<sup>1</sup> David Silver<sup>1</sup> Alex Graves<sup>1</sup> Ioannis Antonoglou<sup>1</sup>Daan Wierstra<sup>1</sup> Martin Riedmiller<sup>1</sup>

DeepMind Technologies

Volodymyr Mnih<sup>1</sup>\*, Koray Kavukcuoglu<sup>1</sup>\*, David Silver<sup>1</sup>\*, Andrei A. Rusu<sup>1</sup>, Joel Veness<sup>1</sup>, Marc G. Bellemare<sup>1</sup>, Alex Graves<sup>1</sup>, Martin Riedmiller<sup>1</sup>, Andreas K. Fiedelnd<sup>1</sup>, Georg Ostrovski<sup>1</sup>, Stig Petersen<sup>1</sup>, Charles Beattie<sup>1</sup>, Amir Sadik<sup>1</sup>, Ioannis Antonoglou<sup>1</sup>, Helen King<sup>1</sup>, Dharshan Kumaran<sup>1</sup>, Daan Wierstra<sup>1</sup>, Shane Legg<sup>1</sup> & Demis Hassabis<sup>1</sup><sup>1</sup>Google DeepMind, 5 New Street Square, London EC4A 3TW, UK  
\*These authors contributed equally to this work.

## ARTICLE

doi:10.1038/nature14061

### Mastering the game of Go with deep neural networks and tree search

David Silver<sup>1</sup>\*, Aja Huang<sup>1</sup>\*, Chris L. Maddison<sup>1</sup>, Arthur Guez<sup>1</sup>, Laurent Sifre<sup>1</sup>, George van den Driessche<sup>1</sup>, Julian Schrittwieser<sup>1</sup>, Ioannis Antonoglou<sup>1</sup>, Yuta Doherty<sup>1</sup>, Vlad Truong<sup>1</sup>, Marc Lanctot<sup>1</sup>, Sander Dieleman<sup>1</sup>, Dominik Grewe<sup>1</sup>, John Schum<sup>1</sup>, Sai Kishore<sup>1</sup>, Ilya Sutskever<sup>1</sup>, Timothy Lillicrap<sup>1</sup>, Madelon Leach<sup>1</sup>, Somya Sundararajan<sup>1</sup>, Thore Graepel<sup>1</sup> & Demis Hassabis<sup>1</sup>

## ARTICLE

doi:10.1038/nature14270

### Mastering the game of Go without human knowledge

David Silver<sup>1</sup>\*, Julian Schrittwieser<sup>1</sup>\*, Karen Simonyan<sup>1</sup>\*, Ioannis Antonoglou<sup>1</sup>, Aja Huang<sup>1</sup>, Arthur Guez<sup>1</sup>, Thomas Hubert<sup>1</sup>, Lucas Baker<sup>1</sup>, Matthew Lai<sup>1</sup>, Adrian Bolton<sup>1</sup>, Yurian Chen<sup>1</sup>, Timothy Lillicrap<sup>1</sup>, Fan Hu<sup>1</sup>, Laurent Sifre<sup>1</sup>, George van den Driessche<sup>1</sup>, Thore Graepel<sup>1</sup> & Demis Hassabis<sup>1</sup>

## A general reinforcement learning algorithm that masters chess, shogi, and Go through self-play

David Silver<sup>1,2,\*†</sup>, Thomas Hubert<sup>1</sup>\*, Julian Schrittwieser<sup>1</sup>\*, Ioannis Antonoglou<sup>1</sup>, Matthew Lai<sup>1</sup>, Arthur Guez<sup>1</sup>, Marc Lanctot<sup>1</sup>, Laurent Sifre<sup>1</sup>, Dharshan Kumaran<sup>1</sup>, Thore Graepel<sup>1</sup>, Timothy Lillicrap<sup>1</sup>, Karen Simonyan<sup>1</sup>, Demis Hassabis<sup>1†</sup>

# Open AI: A New Player

↑ "OpenAI Gym Beta" [↗](#). OpenAI Blog. March 20, 2017. Retrieved March 2, 2018.

↑ "Inside OpenAI, Elon Musk's Wild Plan to Set Artificial Intelligence Free" [↗](#). WIRED. April 27, 2016. Retrieved March 2, 2018. "This morning, OpenAI will release its first batch of AI software, a toolkit for building artificially intelligent systems by way of a technology called "reinforcement learning""

↑ Shead, Sam (April 28, 2016). "Elon Musk's \$1 billion AI company launches a 'gym' where developers train their computers" [↗](#). Business Insider. Retrieved March 3, 2018.

---

## Trust Region Policy Optimization

---

John Schulman  
Sergey Levine  
Philipp Moritz  
Michael Jordan  
Pieter Abbeel

University of California, Berkeley, Department of Electrical Engineering and Computer Sciences

JOSCHU@EECS.BERKELEY.EDU  
SLEVINE@EECS.BERKELEY.EDU  
PCMORITZ@EECS.BERKELEY.EDU  
JORDAN@CS.BERKELEY.EDU  
PABBEEL@CS.BERKELEY.EDU

## Proximal Policy Optimization Algorithms

John Schulman, Filip Wolski, Prafulla Dhariwal, Alec Radford, Oleg Klimov  
OpenAI

{joschu, filip, prafulla, alec, oleg}@openai.com

---

## Reward learning from human preferences and demonstrations in Atari

---

Borja Ibarz  
DeepMind  
bibarz@google.com

Jan Leike  
DeepMind  
leike@google.com

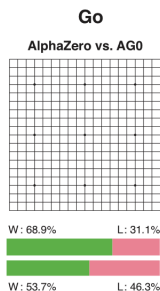
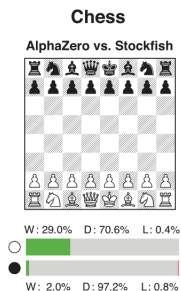
Tobias Pohlen  
DeepMind  
pohlen@google.com

Geoffrey Irving  
OpenAI  
irving@openai.com

Shane Legg  
DeepMind  
legg@google.com

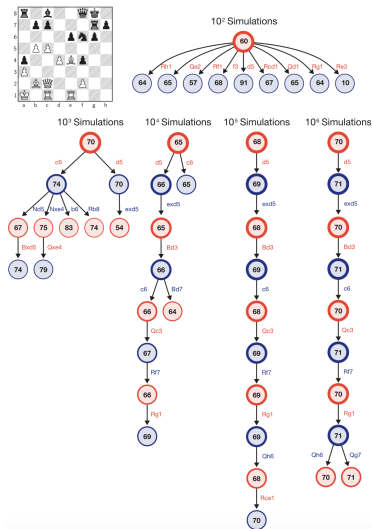
Dario Amodei  
OpenAI  
damodei@openai.com

# Alpha Zero



- *Conventional chess engines used to do depth search via DFS*
- *AlphaZero collect samples via tree search*
  - ↳ *It uses these samples as dataset*
  - ↳ *It learns using an actor-critic method*

# Alpha Zero: Monte Carlo Search Trees



# Legged Robot: Winner of DARPA Subterranean Challenge

*Deep RL used by team CERBERUS to train a legged robot in 2022*



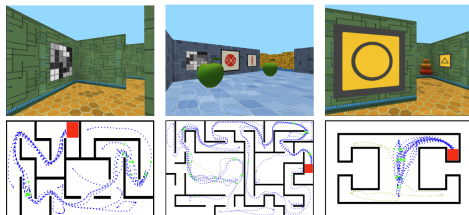
You may check out the details at [this link](#)

# DeepMind: *Learning to Navigate Complex Environments*

## LEARNING TO NAVIGATE IN COMPLEX ENVIRONMENTS

Piotr Mirowski<sup>1</sup>, Razvan Pascanu<sup>2</sup>, Fabio Viola, Hubert Soyer, Andrew J. Ballard,  
Andrea Banino, Misha Denil, Ross Goroshin, Laurent Sifre, Koray Kavukcuoglu,  
Dharshan Kumaran, Raia Hadsell

DeepMind  
London, UK



*DeepMind developed an algorithm for navigation in 2017*

- *It was presented in ICLR 2017: see [the paper](#)*
- *A detailed presentation can be followed on [YouTube](#)*

# DeepMind: Reducing Google Energy Bill by 40%

## Data center cooling using model-predictive control

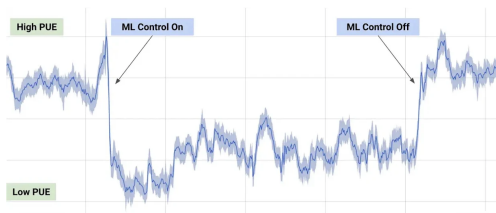
### DeepMind AI Reduces Google Data Centre Cooling Bill by 40%

20 JULY 2016

Richard Evans, Jim Gao

Nevena Lazic, Tyler Lu, Craig Boutilier, Moonkyung Ryu  
Google Research  
{nevena, tylerlu, cboutilier, mkryu}@google.com

Eehern Wong, Binz Roy, Greg Imwalle  
Google Cloud  
{ejwong, binzroy, gregi}@google.com



# DeepMind Blog: *Learn About Cool Applications*

*Check about other cool applications at the [DeepMind Blog](#)*

All categories ▼

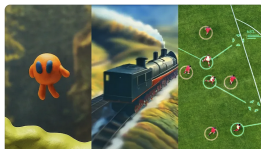


## RESEARCH

**AI achieves silver-medal standard solving International Mathematical Olympiad problems**

Breakthrough models AlphaProof and AlphaGeometry 2 solve advanced reasoning...

25 JULY 2024

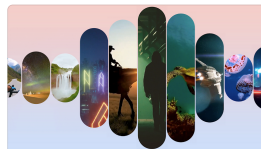


## RESEARCH

**Google DeepMind at ICML 2024**

Exploring AGI, the challenges of scaling and the future of multimodal generative AI

19 JULY 2024



## TECHNOLOGIES

**Generating audio for video**

Video-to-audio research uses video pixels and text prompts to generate rich...

17 JUNE 2024

