Applied Deep Learning

Chapter 6: Recurrent NNs

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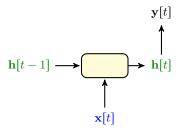
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We have up to now considered unidirectional RNNs

we start from beginning of the sequence and move in one direction



But, can't we learn from future input as well?

Future entries can have information about past: say our RNN wants to fill the empty field

... the color that many people assume is the color of sun ...

Obviously, future input in the sequence is helping in this example!

- + But, how can we get information from future?
- Well, we have the whole sequence: we could move once from left to right and once from right to left

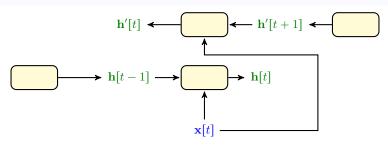
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Bidirectional RNNs

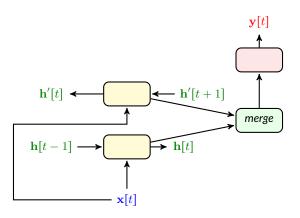
A bidirectional RNN (BRNN) consists of two RNNs

- one that starts with an initial hidden state at t=0 and computes $\mathbf{h}[t]$ from $\mathbf{h}[t-1]$ and $\mathbf{x}[t]$
- another that starts with an initial hidden state at t=T+1 and computes $\mathbf{h'}[t]$ from $\mathbf{h'}[t+1]$ and $\mathbf{x}[t]$

Output at time t is determined from merged version of the two hidden states



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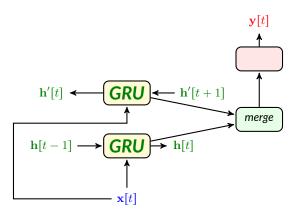


- + What exactly is this merge block?
- It gets the two states and returns a vector that matches output layer

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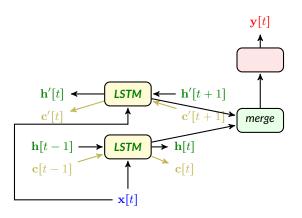
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Bidirectional GRU



- + Should we use any RNN here?
- Sure! We may use GRU

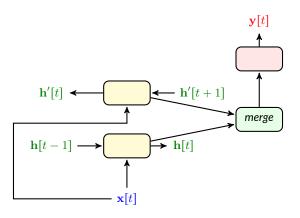
Bidirectional LSTM



- + Should we use any RNN here?
- Sure! We may use LSTM

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RNNs in PyTorch



- + Any suggestion for merging the hidden states?
- Sure! Let's see some code

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RNNs in PyTorch

In PyTorch, we can access a basic RNN in torch.nn module

```
torch.nn.RNN()
```

We can make it deep by simply choosing num_layers more than one and bidirectional by setting bidirectional to True. Same with GRU and LSTM

```
torch.nn.LSTM()
torch.nn.GRU()
```

In bidirectional case, we get access to both states. To merge them, we could

- add the two states
- average them
- concatenate them, i.e., $\mathbf{h}_{\mathrm{c}}[t] = (\mathbf{h}[t], \mathbf{h}'[t])$

or do any other operation that we find useful