ECE 1508: Applied Deep Learning

Chapter 2: Feedforward Neural Networks

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Various Architectures for NNs

Let's abbreviate the term Neural Network from now on with NN

Now that we know what they are and how to train them, we go through

- 1 Feedforward NNs abbreviated as FNNs
 - Some people call them also Multi-Layer Perceptrons (MLPs): you may say that this is a misnomer and you are right! Check the wikipedia page
- 2 Convolutional NNs abbreviated as CNNs
- 3 Recurrent NNs abbreviated as RNNs

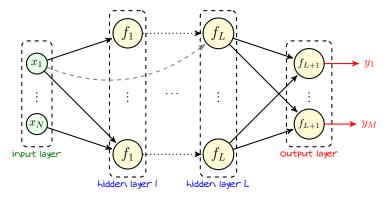
In this chapter, we start with FNNs which are known to be

vanilla NNs,

i.e., the most basic architecture we could think for a NN

FNNs: Architecture

In FNNs, the *inputs flow in one direction*: each layer's output is connected to the next layers, and thus we do not have any feedback



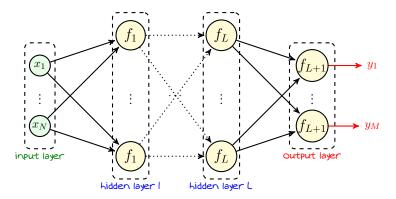
Though it is not a must, we usually use same activation for all neurons in a layer

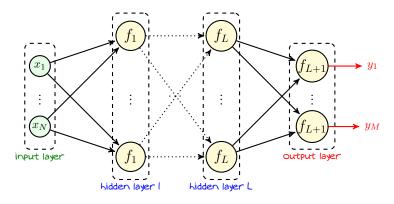
Fully-Connected FNNs

We start with the most straightforward FNNs: fully-connected FNNs

Fully-Connected FNNs

In a fully-connected FNN, each node is connected to all nodes in the next layer



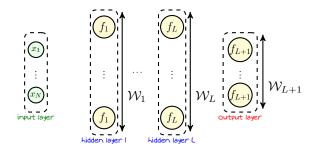


In this FNN, we have L hidden layers; thus, its depth is L+1

Recall: this network is Deep if L > 1

Width of a Layer

The width of layer ℓ is the number of neurons in layer ℓ



Some people call the largest width, the width of the network, i.e.,

$$\mathcal{W} = \max_{\ell \in \{1, \dots, L+1\}} \mathcal{W}_{\ell}$$

Fully-Connected FNNs: Looking as a Model

- + We should look at a fully-connected FNN as a model. Then, what are the hyperparameters and learnable parameters?
- I am glad that you ask! Let's take a look

Assume that someone tells us that we should use a fully-connected FNN with only ReLU activation. Now, we could say

- To write down the model, we need to know the number of hidden layers L and width of each layer \mathcal{W}_{ℓ} : these are the hyperparameters
- If we set the L and W_{ℓ} , we can specify the learnable parameters
 - in hidden layer 1, we have \mathcal{W}_1 neurons each having N weights and a bias
 - ullet in hidden layer 2, we have \mathcal{W}_2 neurons each having \mathcal{W}_1 weights and a bias

ullet in output layer, we have \mathcal{W}_{L+1} neurons each having \mathcal{W}_L weights and a bias

model parameters $= (N+1)\,\mathcal{W}_1 + \sum_{\ell=1}^L \left(\mathcal{W}_\ell + 1\right)\mathcal{W}_{\ell+1}$

7/26

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Let us first see how a given data-point propagates through the FNN: we want to write the outputs y_1, \ldots, y_M when inputs x_1, \ldots, x_N are given

this is called forward propagation through the network

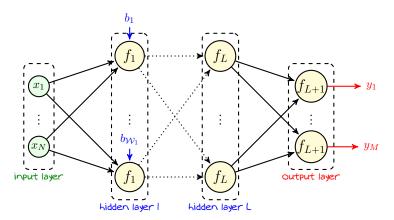
or simply

the forward pass

which tracks values passed through the NN from the input to output layer

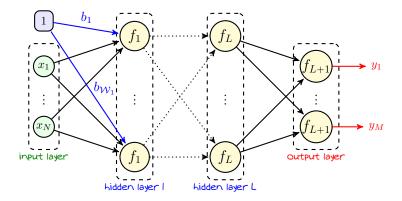
To present forward pass compactly, we need to define some notations and apply some modifications in the network

We can get rid of biases by defining a new constant node in each layer Let's look at the first layer: we have W_1 neurons and each has a bias



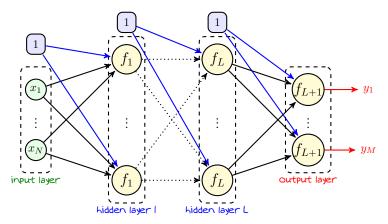
We can get rid of biases by defining a new constant node in each layer

We introduce a constant input and let these biases being the weights of its links



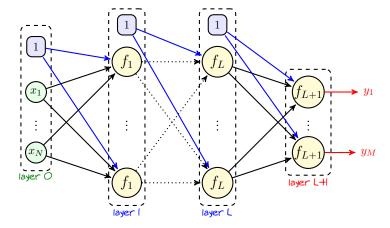
We can get rid of biases by defining a new constant node in each layer

We do the same in all layers: now neurons have no biases



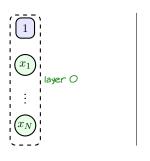
We next give an index to each layer each layer

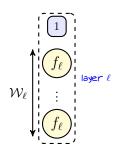
▶ Input layer is layer 0 ▶ Hidden layer ℓ is layer ℓ ▶ Output layer is layer L+1



So, our layers are indexed by $\ell \in \{0, \dots, L+1\}$

- We denote the width of layer ℓ with \mathcal{W}_ℓ
 - $\,\,\,\,\,\,\,\,$ For $\ell\geqslant 1$ this is exactly the layer width \equiv # of neurons in the layer
 - \rightarrow For $\ell = 0$ this is the number of inputs, i.e., $\mathcal{W}_0 = N$
- In layer ℓ , we have $\mathcal{W}_{\ell} + 1$ nodes

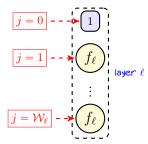




We next index the nodes in each layer

In layer ℓ : we have $\mathcal{W}_{\ell} + 1$ nodes

- \rightarrow One constant node \equiv node j = 0
- \downarrow \mathcal{W}_{ℓ} neurons/inputs \equiv node $j=1,\ldots,\mathcal{W}_{\ell}$

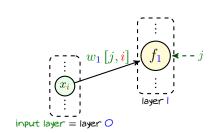


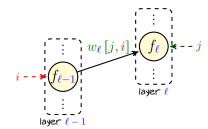
We next give weights to the links

Weight of the link connecting

node i in layer $\ell - 1 \rightarrow$ node j in layer ℓ

is denoted by $w_{\ell}[j, i]$





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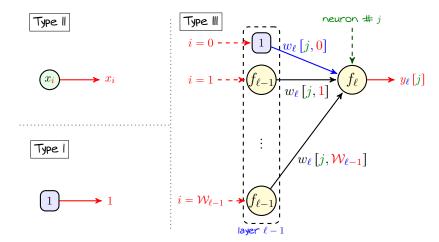
 \downarrow The weights coming out of i = 0 are biases

$$w_{\ell}\left[j,\mathbf{0}\right]$$
 is the bias of neuron j in layer ℓ

- $i = 0, \dots, \mathcal{W}_{\ell-1}$
- $j = 1, \ldots, \mathcal{W}_{\ell}$

This means that there exists no such a weight $w_{\ell}[0,i]$

We finally specify the output of each node



We finally specify the output of each node

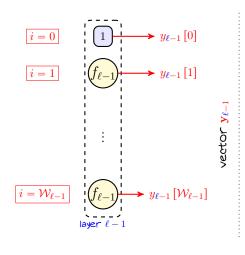
We represent the output of node j in layer ℓ with $y_{\ell}\left[j\right]$

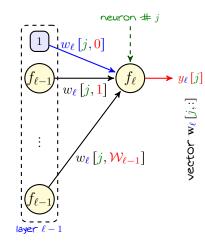
- \rightarrow Since j=0 is the constant node: $y_{\ell}[0]=1$ for $\ell=0,\ldots,L+1$
- \downarrow Since $\ell = 0$ is the input layer: $y_0[j] = x_j$ for j = 1, ..., N
- ightharpoonup For neuron j in layer ℓ we can write

$$y_{\ell}[j] = f_{\ell}(z_{\ell}[j])$$

where $z_{\ell}[j]$ is the output of the affine function in neuron j

$$z_{\ell}[j] = w_{\ell}[j, 0] 1 y_{\ell-1}[0] + \sum_{i=1}^{W_{\ell-1}} w_{\ell}[j, i] y_{\ell-1}[i]$$
$$= \sum_{i=0}^{W_{\ell-1}} w_{\ell}[j, i] y_{\ell-1}[i]$$





We can represent $z_{j}\left[\ell\right]$ more compactly via vectorized notation

$$z_{\ell}[j] = \sum_{i=0}^{\mathcal{W}_{\ell-1}} w_{\ell}[j, i] y_{\ell-1}[i]$$

$$= \underbrace{\begin{bmatrix} w_{\ell}[j, 0] & w_{\ell}[j, 1] & \dots & w_{\ell}[j, \mathcal{W}_{\ell-1}] \end{bmatrix}}_{\mathbf{w}_{\ell}[j, :]^{\mathsf{T}}} \underbrace{\begin{bmatrix} y_{\ell-1}[0] \\ y_{\ell-1}[1] \\ \vdots \\ y_{\ell-1}[\mathcal{W}_{\ell-1}] \end{bmatrix}}_{\mathbf{y}_{\ell-1}}$$

$$= \mathbf{w}_{\ell}[j, :]^{\mathsf{T}} \mathbf{y}_{\ell-1}$$

We can further extend vectorized notation by defining

$$\mathbf{z}_{\ell} = \begin{bmatrix} z_{\ell} [1] \\ \vdots \\ z_{\ell} [\mathcal{W}_{\ell}] \end{bmatrix}$$

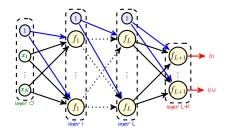
and thus writing \mathbf{y}_{ℓ} as

$$\mathbf{y}_{\ell} = f_{\ell}(\mathbf{z}_{\ell})$$

where $f_{\ell}\left(\cdot\right)$ is applied entry-wise

and don't forget to add the dummy input 1, i.e.,

$$\mathbf{y}_{\ell} \leftarrow \begin{bmatrix} 1 \\ \mathbf{y}_{\ell} \end{bmatrix}$$



```
1: Initiate the output of the first layer as \mathbf{y}_0 = x

2: for \ell = 0, \dots, L do

3: for j = 1, \dots, \mathcal{W}_{\ell+1} do

4: Add y_{\ell}[0] = 1 and set z_{\ell+1}[j] = \mathbf{w}_{\ell+1}[j,:]^\mathsf{T} \mathbf{y}_{\ell} # affine function

5: end for

6: Compute \mathbf{y}_{\ell+1} = f_{\ell+1}(\mathbf{z}_{\ell+1}) # activation

7: end for

8: for \ell = 1, \dots, L+1 do

9: Return \mathbf{y}_{\ell} and \mathbf{z}_{\ell}

10: end for
```

We can present everything even more compactly: let's write down \mathbf{z}_{ℓ}

$$\mathbf{z}_{\ell} = \begin{bmatrix} z_{\ell} [1] \\ \vdots \\ z_{\ell} [\mathcal{W}_{\ell}] \end{bmatrix} = \begin{bmatrix} \mathbf{w}_{\ell} [1,:]^{\mathsf{T}} \mathbf{y}_{\ell-1} \\ \vdots \\ \mathbf{w}_{\ell} [\mathcal{W}_{\ell},:]^{\mathsf{T}} \mathbf{y}_{\ell-1} \end{bmatrix} = \begin{bmatrix} \mathbf{w}_{\ell} [1,:]^{\mathsf{T}} \\ \vdots \\ \mathbf{w}_{\ell} [\mathcal{W}_{\ell},:]^{\mathsf{T}} \end{bmatrix} \mathbf{y}_{\ell-1}$$

Now, we can define the matrix \mathbf{W}_{ℓ} as

$$\mathbf{W}_{\ell} = \begin{bmatrix} \mathbf{w}_{\ell} \begin{bmatrix} 1, : \end{bmatrix}^{\mathsf{T}} \\ \vdots \\ \mathbf{w}_{\ell} \begin{bmatrix} \mathcal{W}_{\ell}, : \end{bmatrix}^{\mathsf{T}} \end{bmatrix} = \begin{bmatrix} w_{\ell} \begin{bmatrix} 1, 0 \end{bmatrix} & \dots & w_{\ell} \begin{bmatrix} 1, \mathcal{W}_{\ell-1} \end{bmatrix} \\ \vdots & & \vdots \\ w_{\ell} \begin{bmatrix} \mathcal{W}_{\ell}, 0 \end{bmatrix} & \dots & w_{\ell} \begin{bmatrix} \mathcal{W}_{\ell}, \mathcal{W}_{\ell-1} \end{bmatrix} \end{bmatrix}$$

This matrix collects all learning parameters of layer ℓ

Note that \mathbf{W}_{ℓ} has \mathcal{W}_{ℓ} rows and $\mathcal{W}_{\ell-1} + 1$ columns

Forward Propagation: Pseudo Code

So, we can compactly present the forward propagation algorithm as follow

```
ForwardProp(): 

1: Initiate with \mathbf{y}_0 = x

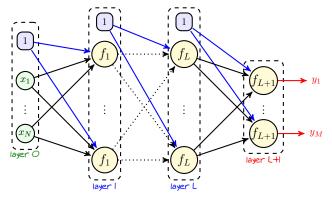
2: \mathbf{for} \ \ell = 0, \dots, L \ \mathbf{do}

3: Add \mathbf{y}_\ell[0] = 1 and determine \mathbf{z}_{\ell+1} = \mathbf{W}_{\ell+1} \mathbf{y}_\ell # forward affine 4: Determine \mathbf{y}_{\ell+1} = f_{\ell+1}(\mathbf{z}_{\ell+1}) # forward activation 5: end for 6: \mathbf{for} \ \ell = 1, \dots, L+1 \ \mathbf{do} 7: Return \mathbf{y}_\ell and \mathbf{z}_\ell 8: end for
```

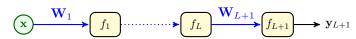
After getting data-point x, we pass it through a linear layer whose weights are learnable and a nonlinear transform that is specified by activation. The output of this layer passes forward to the next layer till we get to the output.

Forward Propagation: Compact Diagram

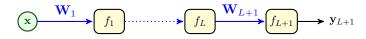
Inspired by forward propagation, we can represent the FNN



by the following compact diagram



Forward Propagation: Compact Diagram



Here, we compactly represent layer ℓ as

$$\begin{bmatrix} 1 \\ \mathbf{y}_{\ell-1} \end{bmatrix} \xrightarrow{\mathbf{W}_{\ell}} \begin{matrix} \mathbf{z}_{\ell} \\ f_{\ell} \end{matrix} \longrightarrow \mathbf{y}_{\ell}$$

- The link \mathbf{W}_{ℓ} represents the affine function of layer ℓ
- The block f_{ℓ} represents the activation of layer ℓ
 - \rightarrow The input of this block can be considered \mathbf{z}_{ℓ}
 - $\,\,\,\,\,\,\,\,$ The output of this block can be considered \mathbf{y}_ℓ
- We always add $y_{\ell}[0] = 1$ after computing \mathbf{y}_{ℓ}

This compact diagram will come in handy when we derive backpropagation!